

# **Programmable Transmitter for Angular Position**

## Unit in field type housing

## **Application**

The **KINAX WT 711** (Figs. 1 and 2) converts the angular position of a shaft into a **load-independent** direct current signal, proportional to the angular position. The unit is **contact-free**. The compact housing has made this unit ideal for building onto other equipment and plant.

### **Features / Benefits**

 Measuring range, sense of rotation, characteristic, switching point and other additional functions programmed using PC / Simplifies project planning and engineering, short delivery times, low stocking

Measured variable	Measuring range limits	
Angular position	Programmable between 0 10 and 0 50 or 0 50 and 0 350 ◀ °	

- Available in type of protection "Intrinsic safety" EEx ia IIC T6 / Can be mounted within the hazardous area (see "Table 3: Data on explosion protection")
- Simulation of measured values / The testing of the subsequent device chain is already possible during the installation phase
- Measured value acquisition / Display of the instantaneous value and a trend graph of the measured value on the screen
- Adjustment / Independent fine adjustment of the analog output, zero position and measuring range
- Characteristic of the output value / Programmable as a linear,
   V-characteristic, or any characteristic curve
- The shaft can be turned through full
- Patented measuring method
- Unit in field type housing / Compact for building onto other equipment and plant

### **Layout and mode of operation**

The transmitter consists of 2 main parts: the differential screen capacitor D and the electronic circuitry E (Fig. 3).

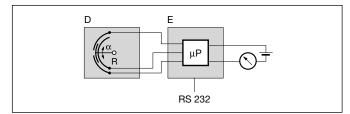


Fig. 3. Block diagram.





II 2 G



Fig. 1. KINAX WT 711 with shaft dia. 2 mm.

Fig. 2. KINAX WT 711 and additional gear.

The angular deflection  $\alpha$  of the device to be measured is transferred to the rotor R of the differential screen capacitor with the aid of a mechanical coupling. It is then converted into a change of capacitance proportional to the angle.

All changes to the position of the rotor result in a change in the capacitance at the input to the microprocessor. This is transformed into a DC current signal proportional to the measured value.

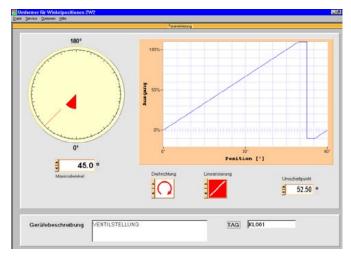


Fig. 4. Print screen example of the menu-controlled programming.

## **Programmable Transmitter for Angular Position**

## **Programming**

A PC, the programming cable PK 610 plus ancillary cable and the configuration software 2W2 are required to program the transmitter. (Details of the programming cable and the software are to be found in the separate data sheet: PK 610 Le).

The connections between

"PC  $\leftrightarrow$  PK 610  $\leftrightarrow$  KINAX WT 711" can be seen from Fig. 5. The transmitter can be programmed either with or without the power supply connected.

The software 2W2 is supplied on one CD and runs under Windows 95 or higher.

The programming cable PK 610 adjusts the signal level between the PC and the transmitter KINAX WT 711.

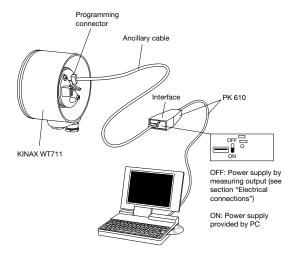


Fig. 5. Example of the set-up for programming a KINAX WT 711 without the power supply. For this case the switch on the interface must be set to "ON".

#### **Technical data**

#### General

Measured quantity: Angle of rotation α **4** °

Capacitive method Measuring principle: Differential screen capacitor with contact-free, non-wearing positional

pick-up. Drive shaft fully rotatable

without stops

(patented measuring method)

**Measuring input** 

Measuring range of

rotation angle:

Programmable between 0 ... 10 and 0 ... 50 **4** °

0 ... 50 and 0 ... 350 **∢** °

Drive shaft diameters: 2 or 6 mm resp. 1/4"

< 0.001 Ncm with shaft dia. 2 mm Frictional torque:

> < 0.03 Ncm with shaft dia. 6 mm resp. 1/4", without additional gear Approx. 0.6 ... 3.2 Ncm with additional gear, depending on transmission

ratio

Sense of rotation

of the drive shaft: Programmable for sense of rotation

clockwise or counterclockwise

**Measuring output** 

Power supply: H = 12 to 33 V DC

(possible with standard version.

non-Ex)

H = 12 to 30 V DC

(necessary with Ex version, type of protection "Intrinsically safe" EEx ia

IIC T6)

Protected against wrong polarity

Load-independent DC current. Output variable I,:

proportional to the input angle

Zero point correction: Approx. ± 5%

Span adjustment: Approx. ± 5% Current limitation: I, max. 40 mA

Standard range: 4...20 mA, two-wire

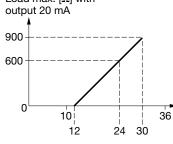
External resistance (load):

 $R_{ext} max. [k\Omega] = \frac{H [V] - 12V}{I_{\Lambda} [mA]}$ 

H = DC power supply

 $I_{\Lambda}$  = End value of output variable

Load max.  $[\Omega]$  with



Power supply [V]

Residual ripple in

output current: < 0.3% p.p. Response time: < 5 ms

#### **Programming connector**

Interface: Serial interface

### **Accuracy data**

Reference value: Measuring span

Error limits at reference Basic accuracy:

conditions  $\leq \pm 0.5\%$ 

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Reproducibility: < 0.2%

# **Programmable Transmitter for Angular Position**

#### Reference conditions

Ambient temperature  $23 \,^{\circ}\text{C} \pm 2 \,^{\circ}\text{K}$ Power supply  $18 \,^{\circ}\text{V}$  DC

Output burden 0  $\Omega$ 

Adjustments 350° version

measuring range > 50...350° characteristic linear

characteristic linear

50° version

measuring range ≥ 10...50°

characteristic linear

Influence effects (maxima)

(included in basic error)

Dependence on external

resistance  $\Delta R_{\text{ext}}$  max.  $\pm 0.1\%$ 

Power supply influence  $\pm 0.1\%$ 

Additional error (maxima)

Temperature influence

 $(-25...+75 \,^{\circ}\text{C})$   $\pm 0.2\% / 10 \,^{\circ}\text{K}$ 

Bearing play influence  $\pm 0.1\%$ 

#### Additional errors (cumulative)

Output characteristic	Definitions	Device version	Additional error
simple "V" characteristic  20 mA —   — — —   — — —   — — —   — — —   — — —   — — —   — — —   — — —   — — —   — —	Angle max. = MW	350°	$f = (\frac{0.18^{\circ}}{MW} \times 100)$
4 mA — — — — — — — — — — — — — — — — — —	Angle min. = 0°	50°	$f = (\frac{0.05^{\circ}}{MW} \times 100)$
"V" characteristic with offset  20 mA —   — —   — — —   — — — — — — — — — —	MS = (angle max.) – (angle min.)	350°	$f = (\frac{0.25^{\circ}}{MS} \times 100)$
4 mA — — — — — — — — — — — — — — — — — —	Angle max. = ± final angle Angle min. = > 0°	50°	$f = (\frac{0.09^{\circ}}{MS} \times 100)$
any characteristic	MS = (angle max.) – (angle min.)	350°	$f = (\frac{0.25^{\circ}}{MS} \times 100)$
4 mA — — — — — — — — — — — — — — — — — —	(angle man)	50°	$f = (\frac{0.09^{\circ}}{MS} \times 100)$

## **Programmable Transmitter for Angular Position**

Installation data

see section "Dimensional dra-

wings"

Housing:

Dimensions:

Field type housing, cast aluminium

Corrosion resistant finish Plastic protection cap

Mounting position:

Electrical connecting

terminals:

Screw-type terminals with indirect

wire pressure,

suited for max. 1.5 mm<sup>2</sup>

1 gland PG9

Weight:

Basic unit alone approx. 0.55 kg with additional gear approx. 0.9 kg

3 cheesehead screws M3 or with Fixation:

3 clamps

**Mechanical withstand** 

Permissible vibrations: acc. to EN 60 068-2-6 Shock: acc. to EN 60 068-2-27

Mounting position: Any

Regulations

Electromagnetic

compatibility: The standards DIN FN 50 081-2 and

DIN EN 50 082-2 are observed

Impulse voltage withstand: 1 kV, 1.2/50 µs, 0.5 Ws

IEC 255-4, Cl. II

IP 43 acc. to EN 60 529 Housing protection:

without gear

IP 64 with gear or other similar

mounting

Test voltage: 500 Veff, 50 Hz, 1 min.

all electrical connections to hou-

sing

Permissible common-

mode voltage: 100 V, 50 Hz

**Environmental conditions** 

Standard version Climatic rating:

> Temperature -25 to + 70 °C Annual mean relative humidity

≤ 75%

Version with improved climatic

rating

Temperature - 25 to + 70 °C Annual mean relative humidity

≤ 95%

Ex version

see Ex-type-examination Certifica-

Transportation and

storage temperature: - 25 to 80 °C

## **Basic configuration**

The transmitter KINAX WT 711 is also available already programmed with a **basic** configuration which is especially recommended in cases where the programming data is not known at the time

of ordering (see "Table 1: Specification and ordering information", feature 5).

### Basic configuration:

Order code	Mechanical angle range	Measuring range	Switching point	Sense of rotation	Characteristic of output variable
711 - 1 <b>1</b> 0X 00XX X	50°	0 50°	55°	Clockwise	Linear
711 - 1 <b>2</b> 0X 00XX X	350°	0 350°	355°	Clockwise	Linear

## Table 1: Specification and ordering information

Features, Selection		Blocking code	no-go with blocking code	Article No./ Feature
Ord	Order code 711 - xxxx xxxx xxxx x			711 –
Version of the transmitter				
	1) Standard			1
	2) EEx ia IIC T6, CENELEC/ATEX, measuring output intrinsically safe	K		2

# **Programmable Transmitter for Angular Position**

Feat	tures, Selection			Blocking code	no-go with blocking code	Article No./ Feature
Orde	er code 711 - xxx	x xxxx xxxx x				711 –
2.	Mechanical angl	e range				
	1) Angle range	to 50°				1
	2) Angle range	> 50 to 350°				2
3.	Sense of rotation					
	0) Sense of rota	ation clockwise		D		0
	1) Sense of rota	ation counterclockwise		E		1
	2) For "V" chara	acteristic		F		2
	Lines 1 and 2: No	ot possible with basic configuration				
4.	Drive shaft					
	0) Standard dia	ı. 2 mm, length 6 mm				0
	1) Special dia.	6 mm, length 6 mm				1
	2) Special dia.	1/4", length 6 mm				2
	A) Transformation	on 1:4, dia.6 mm, length 15 mm			FK	А
	B) Transformation	on 1:1, dia. 6 mm, length 15 mm			FK	В
	C) Transformation	on 4:1, dia. 6 mm, length 15 mm			FK	С
	D) Transformation	on 32 : 1, dia. 6 mm, length 15 mm			FK	D
	E) Transformation	on 64 : 1, dia. 6 mm, length 15 mm			FK	E
5.	Measuring range	)				
	0) Basic configu	uration, programmed		G	EF	0
	9) [°angle], 0 to	final value / switching point:			F	9
	Z) "V" characteristic [± °angle], min/max.:				DE	Z
	Switching point	≥ 10 to 50° with angle range ≥ 50°, > 50 to 350° with angle range > 350° > Final value, max. 60° with angle range ≥ 50°, > Final value, max. 360° with angle range > 350° ≥ 105% final value with non-linear characteristic (lines 1 to 4 in feature 6)				
	Maximal value:	> 0 ≥ 25 with angle range ≥ 50°, Span (max. value – min. value) ≥ 5°; > 25 to 175 with angle range > 350°, span ≥ 25° symmetrical about the center line, e.g. [± angle], min/max.: 15/120 correspond: – 120 to – 15 to 0 to 15 to 120° angle (input) + 20 to 4 to < 4 to 4 to +20 mA (output)				
6.	Characteristic of	foutput variable				
	0) Characteristi	c linear				0
	1) Function X to power of 1/2				FG	1
	2) Function X to power of 3/2				FG	2
	3) Function X to	power of 5/2			FG	3
	4) Customized				FG	4
	Line 4 (on inquiry)	possible with "V" characteristic ): Give an algorithm or fixed points (23 values in 5% s the measuring range, output continuously – 10 to 110				

# **Programmable Transmitter for Angular Position**

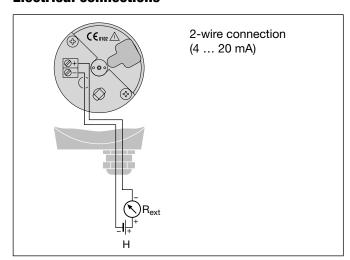
Fea	Features, Selection			no-go with blocking code	Article No./ Feature
Ord	Order code 711 - xxxx xxxx xxxx x				711 –
7.	7. Test certificate				
	O)	Without test certificate			0
	D)	Test certificate in German			D
	E)	Test certificate in English			Е
8.	Mar	king the system zero position			
	O)	System zero position not marked			0
	1)	System zero position marked		G	1
9.	9. Climatic rating				
	O)	Standard climatic rating			0
	1)	Improved climatic rating			1

Lines with letter(s) under "no-go" cannot be combined with preceding lines having the same letter under "Blocking code"

### **Table 2: Data on explosion protection**

Order Code	Type of protection "Intrinsically safe" Marking		Certificates	Mounting location	
	Instrument	Measuring output		of device	
711 - 2	EEx ia IIC T6	$U_{i} = 30 V_{=}$ $I_{i} = 160 \text{ mA}$ $P_{i} = \text{max. 1 W}$ $C_{i} \le 6.6 \text{ nF}$ $L_{i} \approx 0$	Type Examination Certificate ZELM 99 ATEX 0006	Within the hazardous area, zone 1	

#### **Electrical connections**



#### **Application**

- Built onto measuring instruments with rotating pointer shafts, such as pressure gauges, vacuum gauges, absolute and differential pressure gauges as well as dial thermometers (liquid, vapour or mercury types).
- Built into actuator housings for position measurement, such as in valves, gates and butterfly valves.

- Built into transmission housing with float drive for liquid level measurements.
- Measurement of linear motion on coq-rails (racks), cylinder, sliding carriages, floats, nozzle needless etc.

It is particularly suited for fitting on the back of measuring instruments with revolving indicator shaft, because its torque does not exceed 0.001 Ncm and therefore imposes hardly any interaction on the measuring instruments. The drive shaft is mounted in a ball bearing, eliminating friction almost completely. Fig. 6 shows a pressure gauge with measuring transducer fitted, by way of example.



Fig. 6. Pressure gauge fitted with KINAX WT 711 measuring transmitter.

# **Programmable Transmitter for Angular Position**

By fitting an additional gear to the basic unit (see Fig. 7) the measuring range of the transducer can be largely adapted to the measuring duty. Gear ratios range from 1:4 and 64:1. Owing to friction in the gearing and drive shaft, however, this increases the torque to some 0.6 to 3.2 Ncm depending on the transmission ratio. Consequently this combination may be used only with equipment delivering sufficient torque.



Fig. 7. KINAX WT 711 measuring transmitter and additional gear.

#### **Standard accessories**

#### **Transmitter**

- 3 clamps
- 1 protection cap
- 1 blank label
- 1 Operating Instructions in three languages: German, French, English

#### Transmitter with additional gear

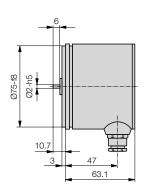
- 3 clamps
- 1 mounting foot
- 2 screws M5 x 10
- 2 spring washer
- 1 blank label
- 1 Operating Instructions in three languages: German, French, English

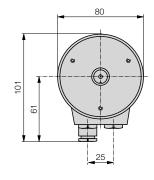
### **Table 3: Accessories and spare parts**

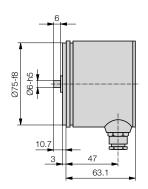
Description	Order No.
Programming cable PK 610	137 887
DSUB 9p F	
Ancillary cable	141 440
1.5 meter	
Configuration software 2W2 Windows 95 or higher on CD in German and English (download free of charge under http://www.camillebauer.ch) In addition, the CD contains all configuration programmes presently available for Camille Bauer products	146 557
Operating Instructions WT 711 Bd-f-e in German, French and English	151 176

### **Dimensional drawings**

#### **Basic unit**







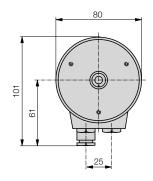


Fig. 8. Basic unit, shaft dia. 2 mm (fixation see Figs. 12 and 13).

Fig. 9. Basic unit, shaft dia. 6 mm (fixation see Figs. 12 and 13). .

# **Programmable Transmitter for Angular Position**

### Basic unit with additional gear

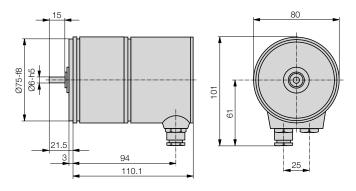


Fig. 10. Basic unit with additional gear (fixation see Fig. 13).

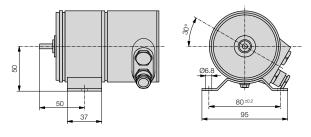
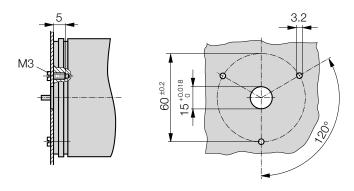
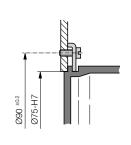


Fig. 11. Fixing with mounting foot. (If the cable glands are in the way when mounted as above, the KINAX WT 710 should be rotated over 120°, after loosening the 3 screws holding the gear).





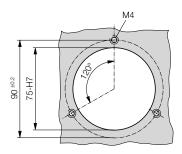


Fig. 12. Left: Fixing with cheesehead screws Right: Drilling plan for cheesehead screws mounting.

Fig. 13. Left: Fixing with clamps Drilling plan for clamp mounting. Right:

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